

Some New Formulas for the Generalized Hypergeometric Series

Sumi P. Krishnan¹, Medhat A. Rakha^{2*}, Arjun K. Rathie¹

(1) *Department of Mathematics, School of Mathematical and Physical Sciences, Central University of Kerala,*

Periyar P.O. Dist. Kasaragod - 671 316, Kerala State - INDIA

(2) *Department of Mathematics, Faculty of Science, Suez Canal University, Ismailia - EGYPT*

Copyright 2015 © Sumi P. Krishnan, Medhat A. Rakha and Arjun K. Rathie. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

Abstract

The aim of this research paper is to provide some new formulas for the generalized hypergeometric series. The results are derived with the help of the extensions of Euler's and Kummer's classical transformations.

As special cases, we have recovered several results due to Sharma. The results established in this paper are simple, interesting, easily obtainable and may be useful.

Keywords: Classical Summation Theorems; Generalized Hypergeometric Series; Euler's Transformation; Kummer's Transformation.

2000 Mathematics Subject Classification. 33C05, 33C20, 33C70

1 Introduction and Results Required

The generalized hypergeometric function ${}_pF_q$ with p numerator parameters and q denominator parameters is defined (see, for example [2, 5]) by

$$\begin{aligned}
 {}_pF_q \left[\begin{matrix} a, & \dots, & a_p; \\ b_1, & \dots, & b_q; \end{matrix} z \right] &= {}_pF_q [a, \dots, a_p; b_1, \dots, b_q; z] \\
 &= \sum_{n=0}^{\infty} \frac{(a_1)_n \dots (a_p)_n z^n}{(b_1)_n \dots (b_q)_n n!}, \quad (1.1)
 \end{aligned}$$

where $(a)_n$ denotes the Pochhammer's symbol (or shifted or raised factorial, since $(1)_n = n!$) defined by

$$(a)_n = \begin{cases} 1, & n = 0, \\ a(a+1) \dots (a+n-1), & n \in \mathbb{N} := \{1, 2, 3, \dots\}. \end{cases} \quad (1.2)$$

By using the fundamental property of the gamma function $\Gamma(a+1) = a\Gamma(a)$, $(a)_n$ can be written in the form

$$(a)_n = \frac{\Gamma(a+n)}{\Gamma(a)}, \quad (a \in \mathbb{C} \setminus \mathbb{Z}_0^-), \quad (1.3)$$

*Corresponding author. Email address: medhat_rakha@science.suez.edu.eg

where \mathbb{C} and \mathbb{Z}_0^- denote the sets of complex numbers and nonpositive integers, respectively.

For more details about the generalized hypergeometric function, see [1, 2, 3].

The following is the well known and very useful result in the theory of generalized hypergeometric series [7]:

$$\begin{aligned}
 {}_pF_q \left[\begin{matrix} a_p; \\ b_q; \end{matrix} x \right] &= {}_{2p}F_{2q+1} \left[\begin{matrix} \frac{1}{2}a_p, & \frac{1}{2}a_p + \frac{1}{2}; \\ \frac{1}{2}, & \frac{1}{2}b_q, & \frac{1}{2}b_q + \frac{1}{2}; \end{matrix} (4)^{p-q-1}x^2 \right] \\
 &+ \frac{(a_p)}{(b_q)} x {}_{2p}F_{2q+1} \left[\begin{matrix} \frac{1}{2}a_p + \frac{1}{2}, & \frac{1}{2}a_p + 1; \\ \frac{3}{2}, & \frac{1}{2}b_q + \frac{1}{2}, & \frac{1}{2}b_q + 1; \end{matrix} (4)^{p-q-1}x^2 \right]. \tag{1.4}
 \end{aligned}$$

We also mention the following two transformations:

- Euler’s II transformation [3, 5]:

$${}_2F_1 \left[\begin{matrix} \alpha, & \beta; \\ \gamma; \end{matrix} x \right] = (1-x)^{\gamma-\alpha-\beta} {}_2F_1 \left[\begin{matrix} \gamma-\alpha, & \gamma-\beta; \\ \gamma; \end{matrix} x \right]. \tag{1.5}$$

- Kummer’s first transformation [5]:

$$e^{-x} {}_1F_1 \left[\begin{matrix} \alpha; \\ \beta; \end{matrix} x \right] = {}_1F_1 \left[\begin{matrix} \beta-\alpha; \\ \beta; \end{matrix} -x \right]. \tag{1.6}$$

By applying (1.4) in the transformations (1.5) and (1.6), Sharma [7] has obtained the following interesting results on the generalized hypergeometric series

$$\begin{aligned}
 &{}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta, & \gamma + \delta - \alpha - \beta + \frac{1}{2}; \\ \frac{1}{2}; \end{matrix} x \right] \\
 &\times {}_4F_3 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \\ \frac{1}{2}, & \gamma, & \gamma + \frac{1}{2}; \end{matrix} x \right] \\
 &+ \left(\frac{\gamma + \delta - \alpha - \beta}{\gamma} \right) 4\alpha\beta x {}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta + \frac{1}{2}, & \gamma + \delta - \alpha - \beta + 1; \\ \frac{3}{2}; \end{matrix} x \right] \\
 &\times {}_4F_3 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1; \\ \frac{3}{2}, & \gamma + \frac{1}{2}, & \gamma + 1; \end{matrix} x \right] \\
 &= {}_2F_1 \left[\begin{matrix} \delta, & \delta + \frac{1}{2}; \\ \frac{1}{2}; \end{matrix} x \right] {}_4F_3 \left[\begin{matrix} \gamma - \alpha, & \gamma - \alpha + \frac{1}{2}, & \gamma - \beta, & \gamma - \beta + \frac{1}{2}; \\ \frac{1}{2}, & \gamma, & \gamma + \frac{1}{2}; \end{matrix} x \right] \\
 &+ \frac{4\delta(\gamma - \alpha)(\gamma - \beta)}{\gamma} x {}_2F_1 \left[\begin{matrix} \delta + \frac{1}{2}, & \delta + 1; \\ \frac{3}{2}; \end{matrix} x \right] \\
 &\times {}_4F_3 \left[\begin{matrix} \gamma - \alpha + \frac{1}{2}, & \gamma - \alpha + 1, & \gamma - \beta + \frac{1}{2}, & \gamma - \beta + 1; \\ \frac{3}{2}, & \gamma + \frac{1}{2}, & \gamma + 1; \end{matrix} x \right]; \tag{1.7}
 \end{aligned}$$

$$\begin{aligned}
 & (\gamma + \delta - \alpha - \beta) {}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta + \frac{1}{2}, & \gamma + \delta - \alpha - \beta + 1; \\ & \frac{3}{2}; \end{matrix} x \right] \\
 & \times {}_4F_3 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \\ \frac{1}{2}, & \gamma, & \gamma + \frac{1}{2}; \end{matrix} x \right] \\
 & + \frac{\alpha\beta}{\gamma} {}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta, & \gamma + \delta - \alpha - \beta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} x \right] \\
 & \times {}_4F_3 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1; \\ \frac{3}{2}, & \gamma + \frac{1}{2}, & \gamma + 1; \end{matrix} x \right] \\
 & = \frac{(\gamma - \alpha)(\gamma - \beta)}{\gamma} {}_2F_1 \left[\begin{matrix} \delta, & \delta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} x \right] \\
 & \times {}_4F_3 \left[\begin{matrix} \gamma - \alpha + \frac{1}{2}, & \gamma - \alpha + 1, & \gamma - \beta + \frac{1}{2}, & \gamma - \beta + 1; \\ \frac{3}{2}, & \gamma + \frac{1}{2}, & \gamma + 1; \end{matrix} x \right] \\
 & + \delta {}_2F_1 \left[\begin{matrix} \delta + \frac{1}{2}, & \delta + 1; \\ & \frac{3}{2}; \end{matrix} x \right] {}_4F_3 \left[\begin{matrix} \gamma - \alpha, & \gamma - \alpha + \frac{1}{2}, & \gamma - \beta, & \gamma - \beta + \frac{1}{2}; \\ \frac{1}{2}, & \gamma, & \gamma + \frac{1}{2}; \end{matrix} x \right]; \tag{1.8}
 \end{aligned}$$

$$\begin{aligned}
 & {}_0F_1 \left[\begin{matrix} -, & \frac{1}{4}a^2 \\ & \frac{1}{2}; \end{matrix} \right] {}_2F_3 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}; \\ \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \end{matrix} \frac{1}{4}a^2 \right] \\
 & + \frac{\alpha ab}{\beta} {}_0F_1 \left[\begin{matrix} -, & \frac{1}{4}b^2 \\ & \frac{3}{2}; \end{matrix} \right] {}_2F_3 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1; \\ \frac{3}{2}, & \beta + \frac{1}{2}, & \beta + 1; \end{matrix} \frac{1}{4}a^2 \right] \\
 & = {}_0F_1 \left[\begin{matrix} -, & \frac{1}{4}(a+b)^2 \\ & \frac{1}{2}; \end{matrix} \right] {}_2F_3 \left[\begin{matrix} \beta - \alpha, & \beta - \alpha + \frac{1}{2}; \\ \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \end{matrix} \frac{1}{4}a^2 \right] \\
 & + \frac{a(\beta - \alpha)(a+b)}{\beta} {}_0F_1 \left[\begin{matrix} -, & \frac{1}{4}(a+b)^2 \\ & \frac{3}{2}; \end{matrix} \right] \\
 & \times {}_2F_3 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, & \beta - \alpha + 1; \\ \frac{3}{2}, & \beta + \frac{1}{2}, & \beta + 1; \end{matrix} \frac{1}{4}a^2 \right]; \tag{1.9}
 \end{aligned}$$

$$\begin{aligned}
 & b_0 F_1 \left[\begin{matrix} - , & \frac{1}{4} b^2 \\ \frac{3}{2}; & \end{matrix} \right] {}_2F_3 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}; \\ \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \\ & & \frac{1}{4} a^2 \end{matrix} \right] \\
 & + \frac{\alpha a}{\beta} {}_0F_1 \left[\begin{matrix} - , & \frac{1}{4} b^2 \\ \frac{1}{2}; & \end{matrix} \right] {}_2F_3 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1; \\ \frac{3}{2}, & \beta + \frac{1}{2}, & \beta + 1; \\ & & \frac{1}{4} a^2 \end{matrix} \right] \\
 & = (a+b) {}_0F_1 \left[\begin{matrix} - , & \frac{1}{4} (a+b)^2 \\ \frac{3}{2}; & \end{matrix} \right] {}_2F_3 \left[\begin{matrix} \beta - \alpha, & \beta - \alpha + \frac{1}{2}; \\ \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \\ & & \frac{1}{4} a^2 \end{matrix} \right] \\
 & + \frac{a(\beta - \alpha)}{\beta} {}_0F_1 \left[\begin{matrix} - , & \frac{1}{4} (a+b)^2 \\ \frac{1}{2}; & \end{matrix} \right] {}_2F_3 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, & \beta - \alpha + 1; \\ \frac{3}{2}, & \beta + \frac{1}{2}, & \beta + 1; \\ & & \frac{1}{4} a^2 \end{matrix} \right]. \tag{1.10}
 \end{aligned}$$

Recently a good progress has been made in generalizing the Euler’s transformation (1.5) and Kummer’s transformation (1.6).

In 2011, Rakha and Rathie [6] obtained the extension of Euler’s II transformation (1.5) in the form:

$${}_3F_2 \left[\begin{matrix} \alpha, & \beta, & d+1; \\ \gamma+1, & d; \end{matrix} \right] x = (1-x)^{\gamma-\alpha-\beta} {}_3F_2 \left[\begin{matrix} \gamma-\alpha, & \gamma-\beta, & 1+g; \\ \gamma+1, & g; \end{matrix} \right] x \tag{1.11}$$

for $d \neq 0, -1, -2, \dots$, $g = f \left(\frac{\alpha - \gamma}{\alpha - f} \right)$ with $f = \frac{d(\beta - \gamma)}{\beta - d}$ and in 2005, Paris [4] obtained the following extension of the Kummer first transformation (1.6) in the form:

$$e^{-x} {}_2F_2 \left[\begin{matrix} \alpha, & c+1; \\ \beta+1, & c; \end{matrix} \right] x = {}_2F_2 \left[\begin{matrix} \beta-\alpha, & f+1; \\ \beta+1, & f; \end{matrix} \right] -x \tag{1.12}$$

for $c \neq 0, -1, -2, \dots$ and $f = \frac{c(\alpha - \beta)}{\alpha - c}$.

The main aim of this paper is to obtain four interesting results involving generalized hypergeometric series by utilizing the results (1.4), (1.11) and (1.12).

Several special cases including the results (1.7) to (1.10) obtained earlier by Sharma [7] have also been given.

The results derived in this paper are simple, interesting, easily established and may be useful.

2 Main Results

The following four general results will be established in this paper:

$$\begin{aligned}
 & {}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta, & \gamma + \delta - \alpha - \beta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} \right. x \left. \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}, & d + 1; \\ \frac{1}{2}, & \gamma + 1, & \gamma + \frac{1}{2}, & d; \end{matrix} \right. x \left. \right] \\
 & + \frac{4(\gamma + \delta - \alpha - \beta)\alpha\beta(d + 1)}{d(\gamma + 1)} x \\
 & \times {}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta + \frac{1}{2}, & \gamma + \delta - \alpha - \beta + 1; \\ & \frac{3}{2}; \end{matrix} \right. x \left. \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1, & d + \frac{3}{2}; \\ \frac{3}{2}, & \gamma + 1, & \gamma + \frac{3}{2}, & d + \frac{1}{2}; \end{matrix} \right. x \left. \right] \\
 & = {}_2F_1 \left[\begin{matrix} \delta, & \delta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} \right. x \left. \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \gamma - \alpha, & \gamma - \alpha + \frac{1}{2}, & \gamma - \beta, & \gamma - \beta + \frac{1}{2}, & g + 1; \\ \frac{1}{2}, & \gamma + 1, & \gamma + \frac{1}{2}, & g; \end{matrix} \right. x \left. \right] \\
 & + \frac{4\delta(\gamma - \alpha)(\gamma - \beta)(1 + g)}{g(\gamma + 1)} x {}_2F_1 \left[\begin{matrix} \delta + \frac{1}{2}, & \delta + 1; \\ & \frac{3}{2}; \end{matrix} \right. x \left. \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \gamma - \alpha + \frac{1}{2}, & \gamma - \alpha + 1, & \gamma - \beta + \frac{1}{2}, & \gamma - \beta + 1, & g + \frac{3}{2}; \\ \frac{3}{2}, & \gamma + 1, & \gamma + \frac{3}{2}, & g + \frac{1}{2}; \end{matrix} \right. x \left. \right]; \tag{2.13}
 \end{aligned}$$

$$\begin{aligned}
 & (\gamma + \delta - \alpha - \beta) {}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta + \frac{1}{2}, & \gamma + \delta - \alpha - \beta + 1; \\ & \frac{3}{2}; \end{matrix} x \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}, & d + 1; \\ \frac{1}{2}, & \gamma + 1, & \gamma + \frac{1}{2}, & d; \end{matrix} x \right] \\
 & + \frac{\alpha\beta(d+1)}{d(\gamma+1)} {}_2F_1 \left[\begin{matrix} \gamma + \delta - \alpha - \beta, & \gamma + \delta - \alpha - \beta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} x \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1, & d + \frac{3}{2}; \\ \frac{3}{2}, & \gamma + 1, & \gamma + \frac{3}{2}, & d + \frac{1}{2}; \end{matrix} x \right] \\
 & = \frac{(\gamma - \alpha)(\gamma - \beta)(1 + g)}{g(\gamma + 1)} {}_2F_1 \left[\begin{matrix} \delta, & \delta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} x \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \gamma - \alpha + \frac{1}{2}, & \gamma - \alpha + 1, & \gamma - \beta + \frac{1}{2}, & \gamma - \beta + 1, & g + \frac{3}{2}; \\ \frac{3}{2}, & \gamma + 1, & \gamma + \frac{3}{2}, & g + \frac{1}{2}; \end{matrix} x \right] \\
 & + \delta {}_2F_1 \left[\begin{matrix} \delta + \frac{1}{2}, & \delta + 1; \\ & \frac{3}{2}; \end{matrix} x \right] \\
 & \times {}_5F_4 \left[\begin{matrix} \gamma - \alpha, & \gamma - \alpha + \frac{1}{2}, & \gamma - \beta, & \gamma - \beta + \frac{1}{2}, & g + 1; \\ \frac{1}{2}, & \gamma + \frac{1}{2}, & \gamma + 1, & g; \end{matrix} x \right]; \tag{2.14}
 \end{aligned}$$

$$\begin{aligned}
 & {}_0F_1 \left[\begin{matrix} -, \\ \frac{1}{2}; \end{matrix} \frac{1}{4}b^2 \right] {}_3F_4 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & c + 1; \\ \frac{1}{2}, & \beta + 1, & \beta + \frac{1}{2}, & c; \end{matrix} \frac{1}{4}a^2 \right] \\
 & + \frac{\alpha\beta(c+1)}{c(\beta+1)} {}_0F_1 \left[\begin{matrix} -, \\ \frac{3}{2}; \end{matrix} \frac{1}{4}b^2 \right] {}_3F_4 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & c + \frac{3}{2}; \\ \frac{3}{2}, & \beta + 1, & \beta + \frac{3}{2}, & c + \frac{1}{2}; \end{matrix} \frac{1}{4}a^2 \right] \\
 & = {}_0F_1 \left[\begin{matrix} -, \\ \frac{1}{2}; \end{matrix} \frac{1}{4}(a+b)^2 \right] {}_3F_4 \left[\begin{matrix} \beta - \alpha, & \beta - \alpha + \frac{1}{2}, & f + 1; \\ \frac{1}{2}, & \beta + \frac{1}{2}, & \beta + 1, & f; \end{matrix} \frac{1}{4}a^2 \right] \\
 & + \frac{a(a+b)(\beta - \alpha)(f+1)}{f(\beta+1)} {}_0F_1 \left[\begin{matrix} -, \\ \frac{3}{2}; \end{matrix} \frac{1}{4}(a+b)^2 \right] \\
 & \times {}_3F_4 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, & \beta - \alpha + 1, & f + \frac{3}{2}; \\ \frac{3}{2}, & \beta + 1, & \beta + \frac{3}{2}, & f + \frac{1}{2}; \end{matrix} \frac{1}{4}a^2 \right]; \tag{2.15}
 \end{aligned}$$

$$\begin{aligned}
 & b {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} \middle| \frac{1}{4}b^2 \right] {}_3F_4 \left[\begin{matrix} \alpha, \alpha + \frac{1}{2}, c + 1; \\ \frac{1}{2}, \beta + 1, \beta + \frac{1}{2}, c; \end{matrix} \middle| \frac{1}{4}a^2 \right] \\
 & + \frac{\alpha a(c+1)}{c(\beta+1)} {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} \middle| \frac{1}{4}b^2 \right] {}_3F_4 \left[\begin{matrix} \alpha + \frac{1}{2}, \alpha + 1, c + \frac{3}{2}; \\ \frac{3}{2}, \beta + 1, \beta + \frac{3}{2}, c + \frac{1}{2}; \end{matrix} \middle| \frac{1}{4}a^2 \right] \\
 & = (a+b) {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} \middle| \frac{1}{4}(a+b)^2 \right] {}_3F_4 \left[\begin{matrix} \beta - \alpha, \beta - \alpha + \frac{1}{2}, f + 1; \\ \frac{1}{2}, \beta + \frac{1}{2}, \beta + 1, f; \end{matrix} \middle| \frac{1}{4}a^2 \right] \\
 & + \frac{a(\beta - \alpha)(f+1)}{f(\beta+1)} {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} \middle| \frac{1}{4}(a+b)^2 \right] \\
 & \times {}_3F_4 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, \beta - \alpha + 1, f + \frac{3}{2}; \\ \frac{3}{2}, \beta + 1, \beta + \frac{3}{2}, f + \frac{1}{2}; \end{matrix} \middle| \frac{1}{4}a^2 \right]. \tag{2.16}
 \end{aligned}$$

3 Derivations

In order to prove our first two results (2.13) and (2.14), we proceed as follows. Writing the result (1.11) in the form

$$(1-x)^{\alpha+\beta-\gamma} {}_3F_2 \left[\begin{matrix} \alpha, \beta, d+1; \\ \gamma+1, d; \end{matrix} \middle| x \right] = {}_3F_2 \left[\begin{matrix} \gamma-\alpha, \gamma-\beta, 1+g; \\ \gamma+1, g; \end{matrix} \middle| x \right]. \tag{3.17}$$

Multiplying both sides of (3.17) by $(1-x)^{-\delta}$, we have

$$\begin{aligned}
 & (1-x)^{\alpha+\beta-\gamma-\delta} {}_3F_2 \left[\begin{matrix} \alpha, \beta, d+1; \\ \gamma+1, d; \end{matrix} \middle| x \right] \\
 & = (1-x)^{-\delta} {}_3F_2 \left[\begin{matrix} \gamma-\alpha, \gamma-\beta, 1+g; \\ \gamma+1, g; \end{matrix} \middle| x \right], \tag{3.18}
 \end{aligned}$$

writing $(1-x)^{-a}$ as ${}_1F_0 \left[\begin{matrix} a; \\ -; \end{matrix} \middle| x \right]$ and using the result (1.4) in the left-hand side as well as in the right-hand side, after some simplification we get

$$\begin{aligned}
 & \left\{ {}_2F_1 \left[\begin{matrix} \frac{1}{2}(\gamma + \delta - \alpha - \beta), & \frac{1}{2}(\gamma + \delta - \alpha - \beta + 1); \\ & \frac{1}{2}; \end{matrix} x^2 \right] \right. \\
 & \left. + (\gamma + \delta - \alpha - \beta) x {}_2F_1 \left[\begin{matrix} \frac{1}{2}(\gamma + \delta - \alpha - \beta + 1), & \frac{1}{2}(\gamma + \delta - \alpha - \beta + 2); \\ & \frac{3}{2}; \end{matrix} x^2 \right] \right\} \\
 & \times \left\{ {}_6F_5 \left[\begin{matrix} \frac{1}{2}\alpha, & \frac{1}{2}\alpha + \frac{1}{2}, & \frac{1}{2}\beta, & \frac{1}{2}\beta + \frac{1}{2}, & \frac{1}{2}(d+1), & \frac{1}{2}(d+1) + \frac{1}{2}; \\ \frac{1}{2}, & \frac{1}{2}(\gamma+1), & \frac{1}{2}(\gamma+1) + \frac{1}{2}, & \frac{1}{2}d, & \frac{1}{2}d + \frac{1}{2}; \end{matrix} x^2 \right] \right. \\
 & \left. + \frac{\alpha\beta(d+1)}{d(\gamma+1)} x {}_6F_5 \left[\begin{matrix} \frac{1}{2}\alpha + \frac{1}{2}, & \frac{1}{2}\alpha + 1, & \frac{1}{2}\beta + \frac{1}{2}, & \frac{1}{2}\beta + 1, \\ \frac{3}{2}, & \frac{1}{2}(\gamma+1) + \frac{1}{2}, & \frac{1}{2}(\gamma+1) + 1, & \frac{1}{2}d + \frac{1}{2}, \\ \frac{1}{2}(d+1) + \frac{1}{2}, & \frac{1}{2}(d+1) + 1; \end{matrix} x^2 \right] \right\} \\
 & \frac{1}{2}d + 1; \\
 & = \left\{ {}_2F_1 \left[\begin{matrix} \frac{1}{2}\delta, & \frac{1}{2}\delta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} x^2 \right] + \delta x {}_2F_1 \left[\begin{matrix} \frac{1}{2}\delta + \frac{1}{2}, & \frac{1}{2}\delta + 1; \\ & \frac{3}{2}; \end{matrix} x^2 \right] \right\} \\
 & \times \left\{ {}_6F_5 \left[\begin{matrix} \frac{1}{2}(\gamma - \alpha), & \frac{1}{2}(\gamma - \alpha) + \frac{1}{2}, & \frac{1}{2}(\gamma - \beta), & \frac{1}{2}(\gamma - \beta) + \frac{1}{2}, & \frac{1}{2}(1 + g), \\ \frac{1}{2}, & \frac{1}{2}(\gamma + 1), & \frac{1}{2}(\gamma + 1) + \frac{1}{2}, & \frac{1}{2}g, & \frac{1}{2}g + \frac{1}{2}; \\ \frac{1}{2}(1 + g) + \frac{1}{2}; \end{matrix} x^2 \right] + \frac{(\gamma - \alpha)(\gamma - \beta)(1 + g)}{g(\gamma + 1)} x \right. \\
 & \times {}_6F_5 \left[\begin{matrix} \frac{1}{2}(\gamma - \alpha) + \frac{1}{2}, & \frac{1}{2}(\gamma - \alpha) + 1, & \frac{1}{2}(\gamma - \beta) + \frac{1}{2}, \\ \frac{3}{2}, & \frac{1}{2}(\gamma + 1) + \frac{1}{2}, & \frac{1}{2}(\gamma + 1) + 1, \\ \frac{1}{2}(\gamma - \beta) + 1, & \frac{1}{2}(1 + g) + \frac{1}{2}, & \frac{1}{2}(1 + g) + 1; \end{matrix} x^2 \right] \left. \right\} \\
 & \frac{1}{2}g + \frac{1}{2}, \quad \frac{1}{2}g + 1;
 \end{aligned}$$

Further replace x by ix , we have

$$\begin{aligned} & \left\{ {}_2F_1 \left[\begin{matrix} \frac{1}{2}(\gamma + \delta - \alpha - \beta), & \frac{1}{2}(\gamma + \delta - \alpha - \beta + 1); \\ & \frac{1}{2}; \end{matrix} (ix)^2 \right] \right. \\ & + (\gamma + \delta - \alpha - \beta)(ix) {}_2F_1 \left[\begin{matrix} \frac{1}{2}(\gamma + \delta - \alpha - \beta + 1), & \frac{1}{2}(\gamma + \delta - \alpha - \beta + 2); \\ & \frac{3}{2}; \end{matrix} (ix)^2 \right] \left. \right\} \\ & \times \left\{ {}_6F_5 \left[\begin{matrix} \frac{1}{2}\alpha, & \frac{1}{2}\alpha + \frac{1}{2}, & \frac{1}{2}\beta, & \frac{1}{2}\beta + \frac{1}{2}, & \frac{1}{2}(d+1), & \frac{1}{2}(d+1) + \frac{1}{2}; \\ \frac{1}{2}, & \frac{1}{2}(\gamma+1), & \frac{1}{2}(\gamma+1) + \frac{1}{2}, & \frac{1}{2}d, & \frac{1}{2}d + \frac{1}{2}; \end{matrix} (ix)^2 \right] \right. \\ & + \frac{\alpha\beta(d+1)}{d(\gamma+1)}(ix) {}_6F_5 \left[\begin{matrix} \frac{1}{2}\alpha + \frac{1}{2}, & \frac{1}{2}\alpha + 1, & \frac{1}{2}\beta + \frac{1}{2}, & \frac{1}{2}\beta + 1, \\ \frac{3}{2}, & \frac{1}{2}(\gamma+1) + \frac{1}{2}, & \frac{1}{2}(\gamma+1) + 1, & \frac{1}{2}d + \frac{1}{2}, \\ \frac{1}{2}(d+1) + \frac{1}{2}, & \frac{1}{2}(d+1) + 1; \end{matrix} (ix)^2 \right] \left. \right\} \\ & = \left\{ {}_2F_1 \left[\begin{matrix} \frac{1}{2}\delta, & \frac{1}{2}\delta + \frac{1}{2}; \\ & \frac{1}{2}; \end{matrix} (ix)^2 \right] + \delta(ix) {}_2F_1 \left[\begin{matrix} \frac{1}{2}\delta + \frac{1}{2}, & \frac{1}{2}\delta + 1; \\ & \frac{3}{2}; \end{matrix} (ix)^2 \right] \right\} \\ & \times \left\{ {}_6F_5 \left[\begin{matrix} \frac{1}{2}(\gamma - \alpha), & \frac{1}{2}(\gamma - \alpha) + \frac{1}{2}, & \frac{1}{2}(\gamma - \beta), & \frac{1}{2}(\gamma - \beta) + \frac{1}{2}, & \frac{1}{2}(1+g), \\ \frac{1}{2}, & \frac{1}{2}(\gamma+1), & \frac{1}{2}(\gamma+1) + \frac{1}{2}, & \frac{1}{2}g, & \frac{1}{2}g + \frac{1}{2}; \\ \frac{1}{2}(1+g) + \frac{1}{2}; \end{matrix} (ix)^2 \right] + \frac{(\gamma - \alpha)(\gamma - \beta)(1+g)}{g(\gamma+1)}(ix) \right. \\ & \times {}_6F_5 \left[\begin{matrix} \frac{1}{2}(\gamma - \alpha) + \frac{1}{2}, & \frac{1}{2}(\gamma - \alpha) + 1, \\ \frac{3}{2}, & \frac{1}{2}(\gamma+1) + \frac{1}{2}, \\ \frac{1}{2}(\gamma - \beta) + \frac{1}{2}, & \frac{1}{2}(\gamma - \beta) + 1, & \frac{1}{2}(1+g) + \frac{1}{2}, & \frac{1}{2}(1+g) + 1; \\ \frac{1}{2}(\gamma+1) + 1, & \frac{1}{2}g + \frac{1}{2}, & \frac{1}{2}g + 1; \end{matrix} (ix)^2 \right] \left. \right\} \end{aligned}$$

On equating real and imaginary parts (and replacing α, β, γ and δ by $2\alpha, 2\beta, 2\gamma$ and 2δ and $-x^2$ by x), we get the results (2.13) and (2.14) respectively. This completes the proof of our first two results (2.13) and (2.14). \square

In exactly the same manner, first by replacing x by ax in (1.12) and multiply both sides by e^{bx} and using the result (1.4), we get (3.17) and (3.18) respectively, so the details of the proof are omitted.

4 Special Cases

In this section, we shall consider several interesting special cases of our main results.

1. In (2.13) and (2.14), if we take $d = \gamma$, then $f = \gamma$ and $g = \gamma$, after some simplification we get, the known results (1.7) and (1.8) (in corrected form) due to Sharma [7].
2. In (2.15) and (2.16), if we take $c = \beta$, then $f = \beta$, after some simplification we get, the known results (1.9) and (1.10) due to Sharma [7].

3. In (2.13) and (2.14), if we put $\delta = 0$, we get the following result:

$$\begin{aligned}
 & {}_5F_4 \left[\begin{matrix} \gamma - \alpha, & \gamma - \alpha + \frac{1}{2}, & \gamma - \beta, & \gamma - \beta + \frac{1}{2}, & g + 1; \\ \frac{1}{2}, & \gamma + \frac{1}{2}, & \gamma + 1, & g; \end{matrix} \right. \\
 & = {}_2F_1 \left[\begin{matrix} \gamma - \alpha - \beta, & \gamma - \alpha - \beta + \frac{1}{2}; \\ \frac{1}{2}; \end{matrix} \right. \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}, & d + 1; \\ \frac{1}{2}, & \gamma + \frac{1}{2}, & \gamma + 1, & d; \end{matrix} \right. \\
 & + \frac{4\alpha\beta(\gamma - \alpha - \beta)(d + 1)}{d(\gamma + 1)} x {}_2F_1 \left[\begin{matrix} \gamma - \alpha - \beta + \frac{1}{2}, & \gamma - \alpha - \beta + 1; \\ \frac{3}{2}; \end{matrix} \right. \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1, & d + \frac{3}{2}; \\ \frac{3}{2}, & \gamma + 1, & \gamma + \frac{3}{2}, & d + \frac{1}{2}; \end{matrix} \right. \quad (4.19)
 \end{aligned}$$

and

$$\begin{aligned}
 & {}_5F_4 \left[\begin{matrix} \gamma - \alpha + \frac{1}{2}, & \gamma - \alpha + 1, & \gamma - \beta + \frac{1}{2}, & \gamma - \beta + 1, & g + \frac{3}{2}; \\ \frac{3}{2}, & \gamma + \frac{3}{2}, & \gamma + 1, & g + \frac{1}{2}; \end{matrix} \right. \\
 & = \frac{g(\gamma - \alpha - \beta)(\gamma + 1)}{(\gamma - \alpha)(\gamma - \beta)(1 + g)} x {}_2F_1 \left[\begin{matrix} \gamma - \alpha - \beta + \frac{1}{2}, & \gamma - \alpha - \beta + 1; \\ \frac{3}{2}; \end{matrix} \right. \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}, & d + 1; \\ \frac{1}{2}, & \gamma + \frac{1}{2}, & \gamma + 1, & d; \end{matrix} \right. \\
 & + \frac{\alpha\beta(d + 1)g(\gamma + 1)}{(\gamma - \alpha)(\gamma - \beta)d(\gamma + 1)(1 + g)} x {}_2F_1 \left[\begin{matrix} \gamma - \alpha - \beta + \frac{1}{2}, & \gamma - \alpha - \beta; \\ \frac{1}{2}; \end{matrix} \right. \\
 & \times {}_5F_4 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1, & d + \frac{3}{2}; \\ \frac{3}{2}, & \gamma + 1, & \gamma + \frac{3}{2}, & d + \frac{1}{2}; \end{matrix} \right. \quad (4.20)
 \end{aligned}$$

Further, in (4.19) and (4.20), if we set $d = \gamma$ then $g = \gamma$, we get the following result due to Sharma [7]

$$\begin{aligned}
 & {}_4F_3 \left[\begin{matrix} \gamma - \alpha, & \gamma - \alpha + \frac{1}{2}, & \gamma - \beta, & \gamma - \beta + \frac{1}{2}; \\ \frac{1}{2}, & \gamma, & \gamma + \frac{1}{2}; \end{matrix} \right. x \left. \right] \\
 &= {}_2F_1 \left[\begin{matrix} \gamma - \alpha - \beta, & \gamma - \alpha - \beta + \frac{1}{2}; \\ \frac{1}{2}; \end{matrix} \right. x \left. \right] {}_4F_3 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \\ \frac{1}{2}, & \gamma, & \gamma + \frac{1}{2}; \end{matrix} \right. x \left. \right] \\
 &+ \frac{4\alpha\beta(\gamma - \alpha - \beta)}{\gamma} {}_x2F_1 \left[\begin{matrix} \gamma - \alpha - \beta + \frac{1}{2}, & \gamma - \alpha - \beta + 1; \\ \frac{3}{2}; \end{matrix} \right. x \left. \right] \\
 &\times {}_4F_3 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1; \\ \frac{3}{2}, & \gamma + \frac{1}{2}, & \gamma + 1; \end{matrix} \right. x \left. \right] \tag{4.21}
 \end{aligned}$$

and

$$\begin{aligned}
 & {}_4F_3 \left[\begin{matrix} \gamma - \alpha + \frac{1}{2}, & \gamma - \alpha + 1, & \gamma - \beta + \frac{1}{2}, & \gamma - \beta + 1; \\ \frac{3}{2}, & \gamma + \frac{1}{2}, & \gamma + 1; \end{matrix} \right. x \left. \right] \\
 &= \frac{\gamma(\gamma - \alpha - \beta)}{(\gamma - \alpha)(\gamma - \beta)} {}_2F_1 \left[\begin{matrix} \gamma - \alpha - \beta + \frac{1}{2}, & \gamma - \alpha - \beta + 1; \\ \frac{3}{2}; \end{matrix} \right. x \left. \right] \\
 &\times {}_4F_3 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \\ \frac{1}{2}, & \gamma, & \gamma + \frac{1}{2}; \end{matrix} \right. x \left. \right] \\
 &+ \frac{\alpha\beta}{(\gamma - \alpha)(\gamma - \beta)} {}_2F_1 \left[\begin{matrix} \gamma - \alpha - \beta, & \gamma - \alpha - \beta + \frac{1}{2}; \\ \frac{1}{2}; \end{matrix} \right. x \left. \right] \\
 &\times {}_4F_3 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & \beta + \frac{1}{2}, & \beta + 1; \\ \frac{3}{2}, & \gamma + \frac{1}{2}, & \gamma + 1; \end{matrix} \right. x \left. \right]. \tag{4.22}
 \end{aligned}$$

4. In (2.15) and (2.16), put $b = 0$ and writing $\frac{1}{4}a^2 = x$, then we get the following results:

$$\begin{aligned}
 & {}_3F_4 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}, & c + 1; \\ \frac{1}{2}, & \beta + 1, & \beta + \frac{1}{2}, & c; \end{matrix} \right. x \left. \right] \\
 &= {}_0F_1 \left[\begin{matrix} -; \\ \frac{1}{2}; \end{matrix} \right. x \left. \right] {}_3F_4 \left[\begin{matrix} \beta - \alpha, & \beta - \alpha + \frac{1}{2}, & f + 1; \\ \frac{1}{2}, & \beta + \frac{1}{2}, & \beta + 1, & f; \end{matrix} \right. x \left. \right] \\
 &+ \frac{4x(\beta - \alpha)(f + 1)}{f(\beta + 1)} {}_0F_1 \left[\begin{matrix} -; \\ \frac{3}{2}; \end{matrix} \right. x \left. \right] \\
 &\times {}_3F_4 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, & \beta - \alpha + 1, & f + \frac{3}{2}; \\ \frac{3}{2}, & \beta + 1, & \beta + \frac{3}{2}, & f + \frac{1}{2}; \end{matrix} \right. x \left. \right] \tag{4.23}
 \end{aligned}$$

and

$$\begin{aligned}
 & {}_3F_4 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1, & c + \frac{3}{2}; \\ \frac{3}{2}, & \beta + 1, & \beta + \frac{3}{2}, & c + \frac{1}{2}; \end{matrix} x \right] \\
 &= \frac{c(\beta + 1)}{\alpha(c + 1)} {}_0F_1 \left[\begin{matrix} -; \\ \frac{3}{2}; \end{matrix} x \right] {}_3F_4 \left[\begin{matrix} \beta - \alpha, & \beta - \alpha + \frac{1}{2}, & f + 1; \\ \frac{1}{2}, & \beta + \frac{1}{2}, & \beta + 1, & f; \end{matrix} x \right] \\
 &+ \frac{(\beta - \alpha)(f + 1)x}{f\alpha(c + 1)} {}_0F_1 \left[\begin{matrix} -; \\ \frac{1}{2}; \end{matrix} x \right] \\
 &\times {}_3F_4 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, & \beta - \alpha + 1, & f + \frac{3}{2}; \\ \frac{3}{2}, & \beta + 1, & \beta + \frac{3}{2}, & f + \frac{1}{2}; \end{matrix} x \right]. \tag{4.24}
 \end{aligned}$$

Further, (4.23) and (4.24) if we set $c = \beta$ then $f = \beta$, we get the following results due to Sharma [7]:

$$\begin{aligned}
 & {}_2F_3 \left[\begin{matrix} \alpha, & \alpha + \frac{1}{2}; \\ \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \end{matrix} x \right] \\
 &= {}_0F_1 \left[\begin{matrix} -; \\ \frac{1}{2}; \end{matrix} x \right] {}_2F_3 \left[\begin{matrix} \beta - \alpha, & \beta - \alpha + \frac{1}{2}; \\ \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \end{matrix} x \right] \\
 &+ \frac{4x(\beta - \alpha)}{\beta} {}_0F_1 \left[\begin{matrix} -; \\ \frac{3}{2}; \end{matrix} x \right] {}_2F_3 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, & \beta - \alpha + 1; \\ \frac{3}{2}, & \beta + 1, & \beta + \frac{1}{2}; \end{matrix} x \right] \tag{4.25}
 \end{aligned}$$

and

$$\begin{aligned}
 & {}_2F_3 \left[\begin{matrix} \alpha + \frac{1}{2}, & \alpha + 1; \\ \frac{3}{2}, & \beta + \frac{1}{2}, & \beta + 1; \end{matrix} x \right] \\
 &= \frac{\beta}{\alpha} {}_0F_1 \left[\begin{matrix} -; \\ \frac{3}{2}; \end{matrix} x \right] {}_2F_3 \left[\begin{matrix} \beta - \alpha, & \beta - \alpha + \frac{1}{2}; \\ \frac{1}{2}, & \beta, & \beta + \frac{1}{2}; \end{matrix} x \right] \\
 &+ \frac{(\beta - \alpha)}{\alpha} {}_0F_1 \left[\begin{matrix} -; \\ \frac{1}{2}; \end{matrix} x \right] {}_2F_3 \left[\begin{matrix} \beta - \alpha + \frac{1}{2}, & \beta - \alpha + 1; \\ \frac{3}{2}, & \beta + 1, & \beta + \frac{1}{2}; \end{matrix} x \right]. \tag{4.26}
 \end{aligned}$$

5. In (2.15) and (2.16), put $\alpha = \beta$ and replacing $\frac{1}{4}b^2 = x^2$ and $\frac{1}{4}a^2 = y^2$, then we get the following result:

$$\begin{aligned}
 & {}_0F_1 \left[\begin{matrix} -; \\ \frac{1}{2}; \end{matrix} (x + y)^2 \right] \\
 &= {}_0F_1 \left[\begin{matrix} -; \\ \frac{1}{2}; \end{matrix} x^2 \right] {}_2F_3 \left[\begin{matrix} \beta, & c + 1; \\ \frac{1}{2}, & \beta + 1, & c; \end{matrix} y^2 \right] \\
 &+ 4xy \frac{\beta(c + 1)}{c(\beta + 1)} {}_0F_1 \left[\begin{matrix} -; \\ \frac{3}{2}; \end{matrix} x^2 \right] {}_2F_3 \left[\begin{matrix} \beta + \frac{1}{2}, & c + \frac{3}{2}; \\ \frac{3}{2}, & \beta + \frac{3}{2}, & c + \frac{1}{2}; \end{matrix} y^2 \right] \tag{4.27}
 \end{aligned}$$

and

$$\begin{aligned}
 & (x+y) {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} (x+y)^2 \right] \\
 &= x {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} x^2 \right] {}_2F_3 \left[\begin{matrix} \beta, c+1; \\ \frac{1}{2}, \beta+1, c; \end{matrix} y^2 \right] \\
 &+ \frac{\beta(c+1)}{c(\beta+1)} y {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} x^2 \right] {}_2F_3 \left[\begin{matrix} c+\frac{3}{2}, \beta+\frac{1}{2}; \\ \frac{3}{2}, c+\frac{1}{2}, \beta+\frac{3}{2}; \end{matrix} y^2 \right]. \tag{4.28}
 \end{aligned}$$

Further, in (4.27) and (4.28), if we set $c = \beta$, we get the following results due to Sharma [7]:

$$\begin{aligned}
 {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} (x+y)^2 \right] &= {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} x^2 \right] {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} y^2 \right] \\
 &+ 4xy {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} x^2 \right] {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} y^2 \right] \tag{4.29}
 \end{aligned}$$

and

$$\begin{aligned}
 (x+y) {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} (x+y)^2 \right] &= x {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} x^2 \right] {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} y^2 \right] \\
 &+ y {}_0F_1 \left[\begin{matrix} - \\ \frac{1}{2}; \end{matrix} x^2 \right] {}_0F_1 \left[\begin{matrix} - \\ \frac{3}{2}; \end{matrix} y^2 \right]. \tag{4.30}
 \end{aligned}$$

Similarly, other results can be obtained.

5 Conflict of Interests

The authors declare that they have no any conflict of interests.

Acknowledgments

All authors contributed equally in this paper. They read and approved the final manuscript.

References

- [1] G. E. Andrews, R. Askey, R. Roy, Special Functions, Encyclopedia of Mathematics and its applications, Cambridge university press, (1999).
- [2] W. N. Bailey, Generalized Hypergeometric Series, Cambridge University Press, (1935); Reprinted by Hafner Pub. Co., New York, (1972).
- [3] A. Erdelyi, et al; Higher Transcendental Functions, Vol. 1, McGraw Hill Company, New York, (1953).
- [4] R. B. Paris, A Kummer type transformation for a ${}_2F_2$ hypergeometric function, J. Comput. Appl. Math, 173 (2) (2005) 379-382.
<http://dx.doi.org/10.1016/j.cam.2004.05.005>

- [5] E. D. Rainville, Special functions, The Macmillan company, New York, (1960).
- [6] M. A. Rakha, A. K. Rathie, Extensions of Euler type II transformation and Saalschutz's theorem, Bull. Korean Math. Soc, 48 (1) (2011) 151-156.
<http://dx.doi.org/10.4134/BKMS.2011.48.1.151>
- [7] B. L. Sharma, Some new formula for hypergeometric series, Kyungpook Math. J, 16 (1) (1976) 95-99.